

Resource Allocation for Intelligent Reflecting Surface Enabled Heterogeneous Networks

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Abstract

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Abstract—Intelligent reflecting surface (IRS)-enabled communication systems provide higher system capacity and spectral efficiency by reflecting the incident signals from transmitters in a low-cost passive reflecting way. However, it poses new challenges in resource allocation due to surrounding interference and phase shift, especially when IRS is employed in heterogeneous networks (HetNets). In this paper, a joint power allocation and phase shift optimization problem is studied for the downlink IRS-enabled HetNet, in which the IRS is deployed to enhance the communications between small cell users (SCUs) and associated base station (BS). The signal-to-interference-plus-noise ratio (SINR) received at the SCU is maximized by jointly optimizing the transmit power of the small-cell BS and the phase shift of the IRS, subject to the constraints on the minimum SINR requirement of the macro-cell user (MCU) and the phase shift. Although the formulated problem is non-convex, we develop an optimal power allocation and the IRS's passive array coefficient solution for the single-user scenario. For the multi-user scenario, we propose an iterative algorithm to maximize the total rates of SCUs for obtaining a suboptimal solution by an alternating iteration manner, where the sum of multiple-ratio fractional programming problem is converted into a convex semidefinite program (SDP) problem. Simulation results show that the proposed algorithm significantly improves the achieved transmission rates of SCUs compared to the case without the IRS.

Index Terms—Heterogeneous network (HetNet), intelligent reflecting surface (IRS), phase shift, power allocation, resource allocation.

I. INTRODUCTION

INTELLIGENT reflecting surface (IRS) consists of a large number of low-cost passive reflecting elements, which has been considered as a promising technology to enhance the spectrum and energy efficiency as well as to

realize cost-efficient wireless networks by reconfiguring the wireless propagation environment [1]–[4]. Particularly, each IRS element can reflect and change the phase shift of the incident signal from the base station (BS) in a passive way [5]. This approach can achieve three-dimensional (3D) passive beamforming without the need of any transmit radio-frequency (RF) chain [6]. Since the IRS is connected with the BS through an IRS controller, the reflected signal propagation can be smartly configured to meet the communication requirements, i.e., maximizing the system capacity and enhancing transmission security.

A. Related Work

For the resource allocation (RA) problem in HetNets, the key issue is to determine power allocation and user association strategies for obtaining good system capacity and achieving interference management [7]–[10]. However, for the IRS-based HetNets, phase shift of reflecting elements at the IRS should be optimized for interference management and system capacity improvement. The RA problems for IRS-enabled wireless networks have attracted great attention, in which the major efforts have been put on enhancing system secrecy and spectrum efficiency. For the single-user IRS-based multiple-input single-output (MISO) system with single eavesdropper, transmit power minimization and secrecy rate maximization have been studied in [11] and [12], respectively. Extended to the multi-user scenario, the secrecy rate maximization under one eavesdropper and the max-min secrecy rate under multiple eavesdroppers have been discussed in [13] and [14], respectively.

In addition to RA for secrecy communications, spectrum efficiency and energy efficiency have been widely investigated for the IRS-enabled systems. Particularly, the spectrum efficiency of a point-to-point IRS-assisted MISO communication system is maximized by optimizing the beamformer at the access point (AP) and the phase shift of the IRS in [15]. For an IRS-based multiuser MISO system, the energy efficiency (EE) of users is maximized in [16] by using the alternating optimization method (AOM). In [17], the total transmit power at the AP has been minimized for an IRS-aided single-cell wireless system, in which one IRS is deployed to facilitate the transmissions between an AP equipped with multiple antennas and multiple users, each is equipped with a single antenna. The suboptimal transmit beamforming of the active antenna array at the AP and the reflect beamforming of passive phase shifters have been achieved by using the AOM. Moreover,

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due to the advantage of IRS in capacity improvement, it has also been adopted to enhance the performance of various communication systems, such as Terahertz communication system [18], simultaneous wireless information and power transfer (SWIPT) system [19], [20], and non-orthogonal multiple access (NOMA) system [21]–[23]. The summary of existing work and comparison of the problem formulation along with solution domains is provided in Table I.

B. Motivation and Contributions

It is well-known that HetNets can obviously improve system coverage and network capacity gain by deploying small cells underlying the macrocell network [24]–[26]. The power allocation and beamforming design at the small cell BS (SBS) is applicable to improve the communication quality of indoor users and suppress the mutual interference or inter-cell interference (ICI) [27], [28]. However, the quality of service (QoS) of small-cell users (SCUs) can be heavily degraded by interior walls or strong fading channels, such as non-line of sight (NLOS). The IRS can be placed in such scenarios for improving the wireless signal strength. Hence, it is strongly desirable to explore the use of IRS to provide additional paths and construct stronger combined channels by intelligently adjusting the phase shifts of the passive IRS elements.

Motivated by the above, in this paper, we consider the downlink transmissions in an IRS-enabled HetNet where an SBS overlaying in the macrocell transmits signals to multiple SCUs and the IRS. The performance improvement of the single-antenna SCU is achieved through the IRS that forwards a suitable phase-shifted version of the transmitted signal from the SBS. To the best of our knowledge, the RA for such a system is still in its infancy. The contributions of this paper are summarized as follows:

- We investigate an IRS-enabled HetNet with two tiers where a single-antenna SBS transmits superposed signals to multiple single-antenna SCUs with the assistance of an IRS. For the single SCU scenario, the signal-to-interference-plus-noise ratio (SINR) received at the SCU is maximized by jointly optimizing the transmit power of the SBS and the phase shifts of IRS elements under the SINR constraint of the macrocell user (MCU) and the phase shift constraint. An Dinkelbach-based optimal iteration algorithm is proposed to solve the problem.
- For the multi-user scenario, the sum rate of SCUs is maximized by jointly optimizing the transmit power and phase shift. To tackle the coupled variables in the objective function and constraints, we propose an efficient algorithm based on the semidefinite programming (SDP) technique and successive convex approximation (SCA) to obtain a suboptimal solution in an alternating iteration manner.
- Simulation results show that IRS can improve the transmission rate of SCUs significantly, even for the scenario where the direct links of users are weak.

The rest of this paper is organized as follows. In Section II, the system model of the IRS-enabled HetNet is described and the RA problem for the single-user scenario is formulated and

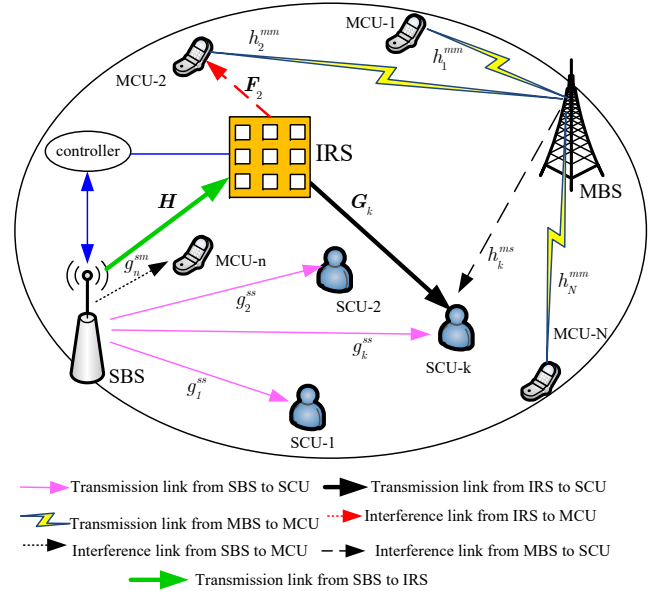


Fig. 1. An IRS-enhanced heterogeneous wireless network.

solved optimally. Section III formulates the RA problem for the multi-user case and provides a suboptimal solution. Section IV presents simulation results to show the effectiveness of the proposed algorithms. Finally, the concludes and future research direction are drawn in Section V.

II. SYSTEM MODEL AND SINGLE-USER RESOURCE ALLOCATION

A. System Model

We consider the downlink transmission of the IRS-enabled HetNet, where an IRS is employed to enhance the transmission performance between the SBS and SCUs, as illustrated in Fig. 1. It is assumed that the IRS comprises M passive reflecting units, denoted as $\mathcal{M} = \{1, 2, \dots, M\}$, $\forall m \in \mathcal{M}$, and is connected to a controller, which adjusts the IRS pattern for the desired signal reflection. A separate wireless control link serves for information exchange between the IRS controller and the SBS on the channel state information (CSI) and other information needed for implementing the joint design of the SBS transmit power and IRS reflection with the QoS guaranteed by the MCU [20]. We assume that the CSI is available at the BS via channel training or feedback from the users and the IRS [11], [12].

Define $\mathbf{H} = [h_1, h_2, \dots, h_M]^T \in \mathcal{C}^M$ and $\mathbf{G} = [g_1, g_2, \dots, g_M]^T \in \mathcal{C}^M$ as the channel gain from the SBS to the IRS and the IRS to the SCU, and denote h^{mm} and h^{ms} as the channel gain from the MBS to the MCU and the MBS to the SCU. Define g^{sm} and g^{ss} as the channel gain from the SBS to the MCU and the SBS to the SCU. Define $\mathbf{F} = [f_1, f_2, \dots, f_M]^T \in \mathcal{C}^M$ as the channel gain from the IRS to the MCU. Define $\boldsymbol{\phi} = [\phi_1, \phi_2, \dots, \phi_M]^H$ as the IRS reflection coefficients, where each $\phi_m = \beta_m e^{j\theta_m}$ comprises an amplitude coefficient $\beta_m \in [0, 1]$ and a phase shift $\theta_m \in [0, 2\pi)$ of the m -th reflecting element, and $|\phi_m| = 1$. Define $\boldsymbol{\Phi} = \text{diag}(\boldsymbol{\phi}) \in \mathcal{C}^{M \times M}$ as the reflection

TABLE I
SUMMARY OF RA IN IRS-BASED SYTEMS.

Ref.	Type	Network Scenario	Problem	Interference Type	Optimal variable	Solution
[17]	single-tier	multiuser IRS-based MISO system	min: total transmit power	inter-cell interference	beamforming and RC	suboptimal, closed-form
[15]	single-tier	single-user IRS-based MISO system	max: data rate	inter-cell interference	beamforming and RC	suboptimal, no close-form
[16]	single-tier	multiuser IRS-based MISO system	max: EE	inter-cell interference	power allocation and RC	suboptimal, no close-form
[18]	single-tier	multiuser IRS-based MISO system	max: sum rate	inter-cell interference	beamforming and RC	suboptimal, no close-form
[19]	single-tier	multiuser MISO IRS-SWIPT system	min: total transmit power	Inter-cell interference	beamforming and RC	suboptimal, close-form
[20]	single-tier	multiuser MIMO IRS-SWIPT system	max: weighted sum rate	inter-cell interference	beamforming and RC	suboptimal, close-form
[21]	single-tier	multiuser SISO IRS-NOMA system	max-min: SINR	inter-cell interference	power allocation and RC	suboptimal, no close-form
[22]	single-tier	multiuser MISO IRS-NOMA system	max: sum rate	inter-cell interference	beamforming and RC	suboptimal, no close-form
[23]	single-tier	multiuser MISO IRS-NOMA system	min: total transmit power	inter-cell interference	beamforming and RC	suboptimal, no close-form
in this paper	two-tier	multiuser IRS-based HetNets	max: sum rate	inter-cell interference, cross-tier interference	power allocation and RC	optimal and suboptimal, closed-form

coefficient matrix of the IRS. Since we aim to obtain the maximum designed signal, therefore, the amplitude coefficient is set as $\beta_m = 1$ for simplicity [17]. As a result, we only need to optimize the phase shift of each IRS element. We denote P and p as the transmit power at the MBS and the SBS, respectively. Correspondingly, the SINRs received at the SCU and the MCU are

$$\gamma^{\text{SCU}} = \frac{p|\mathbf{G}^H \mathbf{\Phi} \mathbf{H} + g^{ss}|^2}{Ph^{ms} + \sigma^2}, \quad (1)$$

and

$$\gamma^{\text{MCU}} = \frac{Ph^{mm}}{p|g^{sm} + \mathbf{F}^H \mathbf{\Phi} \mathbf{H}|^2 + \sigma^2}. \quad (2)$$

where $(\cdot)^H$ denotes the conjugate transpose of a vector.

B. Single-user Resource Allocation Algorithm

In the IRS-enabled HetNet, we improve the QoS of SCU by adjusting the transmit power, meanwhile, the QoS of the MCU needs to be guaranteed. Since the data rate of user is in proportion to the SINR. Thus, the max-SINR of SCU with the MCU's QoS constraint is given by

$$\begin{aligned} \mathbf{P1} \quad & \max_{p, \theta_m} \gamma^{\text{SCU}} \\ & \text{s.t. } C_1 : \gamma^{\text{MCU}} \geq \gamma^{\min}, \\ & \quad C_2 : 0 \leq \theta_m \leq 2\pi, \forall m, \\ & \quad C_3 : 0 \leq p \leq p^{\max}, \end{aligned}$$

where C_1 denotes the QoS required by the MCU under the interference from the IRS and the SBS, $\gamma^{\min}$ represents the SINR threshold of the MCU, C_2 denotes the phase shift constraint at the IRS, C_3 denotes the transmit power range of the SBS, and $p^{\max}$ is the maximum transmit power at the SBS. Since we focus on finding the optimal power p and phase shift θ_m , the maximum transmit power limit at the MBS is omitted here.

According to C_1 , we have the upper bound of p , that is

$$p \leq \frac{Ph^{mm} - \gamma^{\min} \sigma^2}{\gamma^{\min} |g^{sm} + \mathbf{F}^H \mathbf{\Phi} \mathbf{H}|^2}. \quad (3)$$

According to the monotonicity of p , we have the optimal power allocation strategy

$$p^* = \min \left(p^{\max}, \frac{Ph^{mm} - \gamma^{\min} \sigma^2}{\gamma^{\min} |g^{sm} + \mathbf{F}^H \mathbf{\Phi} \mathbf{H}|^2} \right). \quad (4)$$

By substituting the optimal p^* in (4) into the problem **P1**,

we have the following optimization problem, i.e.,

$$\begin{aligned} \mathbf{P2} \quad & \max_{\theta_m} \frac{A|\mathbf{G}^H \mathbf{\Phi} \mathbf{H} + g^{ss}|^2}{|g^{sm} + \mathbf{F}^H \mathbf{\Phi} \mathbf{H}|^2} \\ & \text{s.t. } C_2 : 0 \leq \theta_m \leq 2\pi, \forall m, \end{aligned}$$

where $A = \frac{Ph^{mm} - \gamma^{\min} \sigma^2}{\gamma^{\min} (Ph^{ms} + \sigma^2)}$ if $p^* < p^{\max}$, otherwise $A = p^{\max}$. It is a fractional form which belongs to a nonlinear fractional program [29]. Without loss of generality, we define the optimal objective function as

$$\lambda^* = \frac{A|\mathbf{G}^H \mathbf{\Phi} \mathbf{H} + g^{ss}|^2}{|g^{sm} + \mathbf{F}^H \mathbf{\Phi} \mathbf{H}|^2}. \quad (5)$$

We are now ready to introduce the following Theorem.

Theorem 1: The maximum objective value λ^* can be achieved if and only if

$$\begin{aligned} & \max_{\phi_m} A|\mathbf{G}^H \mathbf{\Phi} \mathbf{H} + g^{ss}|^2 - \lambda^* |g^{sm} + \mathbf{F}^H \mathbf{\Phi} \mathbf{H}|^2 \\ & = A|\mathbf{G}^H \mathbf{\Phi}^* \mathbf{H} + g^{ss}|^2 - \lambda^* |g^{sm} + \mathbf{F}^H \mathbf{\Phi}^* \mathbf{H}|^2 \\ & = 0. \end{aligned} \quad (6)$$

where $\{\phi_m\}$ is any feasible solution of **P2** to satisfy the constraint C_2 , $\mathbf{\Phi}^*$ is the optimal phase shift reflection coefficients.

Proof: See Appendix A.

Theorem 1 shows that for an optimization problem with a fractional objective function, there exists an equivalent function in subtractive form, e.g., $A|\mathbf{G}^H \mathbf{\Phi} \mathbf{H} + g^{ss}|^2 - \lambda^* |g^{sm} + \mathbf{F}^H \mathbf{\Phi} \mathbf{H}|^2$ in the considered case. As a result, we focus on the equivalent objective function in the rest of the paper.

Based on the Dinkelbach's method [29], we obtain the following equivalent optimization problem

$$\begin{aligned} \mathbf{P3} \quad & \max_{\phi_m} A|\mathbf{G}^H \mathbf{\Phi} \mathbf{H} + g^{ss}|^2 - \lambda |g^{sm} + \mathbf{F}^H \mathbf{\Phi} \mathbf{H}|^2 \\ & \text{s.t. } \bar{C}_2 : |\phi_m| = 1, \forall m. \end{aligned}$$

The objective function in **P3** is a strictly continuous and decreasing function with respect to the variable λ .

Theorem 2: For any $\mathbf{\Phi}$ and λ , $Q(\lambda) = \max_{\phi_m} A|\mathbf{G}^H \mathbf{\Phi} \mathbf{H} + g^{ss}|^2 - \lambda |g^{sm} + \mathbf{F}^H \mathbf{\Phi} \mathbf{H}|^2$ is a strictly monotonic decreasing function with respect to the variable λ , and $Q(\lambda) \geq 0$.

Proof: See Appendix B.

Since $\phi = [\phi_1, \phi_2, \dots, \phi_M]^H$, $\bar{\mathbf{G}} = \text{diag}(\mathbf{G})\mathbf{H}$ and $\bar{\mathbf{F}} =$

$\text{diag}(\mathbf{F})\mathbf{H}$. **P3** becomes

$$\begin{aligned} \bar{\mathbf{P3}} \quad & \max_{\phi_m} \phi^H (A\bar{\mathbf{G}}\bar{\mathbf{G}}^H - \lambda\bar{\mathbf{F}}\bar{\mathbf{F}}^H) \phi + A|g^{ss}|^2 - \lambda|g^{sm}|^2 \\ & + \text{Re}\{(Ag^{ss}\bar{\mathbf{G}}^H - \lambda g^{sm}\bar{\mathbf{F}}^H) \phi\} \\ & + \text{Re}\{\phi^H (Ag^{ss}\bar{\mathbf{G}} - \lambda g^{sm}\bar{\mathbf{F}})\} \\ \text{s.t. } & \bar{C}_2 : |\phi_m| = 1. \end{aligned}$$

Define $\tilde{\mathbf{G}} = A\bar{\mathbf{G}}\bar{\mathbf{G}}^H - \lambda\bar{\mathbf{F}}\bar{\mathbf{F}}^H \in \mathcal{C}^{M \times M}$, $\bar{\mathbf{H}} = Ag^{ss}\bar{\mathbf{G}} - \lambda g^{sm}\bar{\mathbf{F}} \in \mathcal{C}^M$, and $\bar{A} = A|g^{ss}|^2 - \lambda|g^{sm}|^2$, then $\bar{\mathbf{P3}}$ becomes

$$\begin{aligned} \mathbf{P4} \quad & \max_{\phi_m} \phi^H \tilde{\mathbf{G}} \phi + \text{Re}\{\phi^H \bar{\mathbf{H}}\} + \text{Re}\{\bar{\mathbf{H}}^H \phi\} + \bar{A} \\ \text{s.t. } & \bar{C}_2 : |\phi_m| = 1. \end{aligned}$$

Note that **P4** is a non-convex quadratically constrained quadratic program (QCQP) problem, which can be converted into a homogeneous QCQP problem.

Specifically, by introducing an auxiliary variable t , **P4** can be equivalently rewritten as

$$\begin{aligned} \bar{\mathbf{P4}} \quad & \max_{\bar{\phi}_m} \bar{\phi}^H \mathbf{M} \bar{\phi} + \bar{A} \\ \text{s.t. } & \bar{C}_2 : |\bar{\phi}_m| = 1, \end{aligned}$$

where

$$\mathbf{M} = \begin{bmatrix} \tilde{\mathbf{G}} & \bar{\mathbf{H}} \\ \bar{\mathbf{H}}^H & 0 \end{bmatrix} \text{ and } \bar{\phi} = \begin{bmatrix} \phi \\ t \end{bmatrix}. \quad (7)$$

However, $\bar{\mathbf{P4}}$ is still non-convex. Note that $\bar{\phi}^H \mathbf{M} \bar{\phi} = \text{Trace}(\mathbf{M} \bar{\phi} \bar{\phi}^H)$. Define $\mathbf{X} = \bar{\phi} \bar{\phi}^H$, which satisfies $\mathbf{X} \succeq 0$ and $\text{rank}(\mathbf{X}) = 1$. As a result, problem $\bar{\mathbf{P4}}$ becomes

$$\begin{aligned} \mathbf{P5} \quad & \max_{\mathbf{X}} \text{Trace}(\mathbf{M} \mathbf{X}) + \bar{A} \\ \text{s.t. } & \bar{C}_3 : \mathbf{X}_m = 1, \forall m, \\ & C_4 : \mathbf{X} \succeq 0. \end{aligned}$$

P5 is a convex SDP problem, it can be efficiently solved by using the convex optimization tool, such as SeDuMi [33] and YALMIP [34].

Generally, the solution $\mathbf{X}$ of **P5** may not satisfy its rank constraint, namely, $\text{rank}(\mathbf{X}) \neq 1$, therefore the optimal objective value of **P5** only serves an upper bound of **P4**. To solve this problem and obtain a rank-one solution, the Gaussian randomization scheme and the singular-value-decomposition scheme are used [17], [21], [35]. The iterative RA algorithm is summarized in Algorithm 1.

III. MULTI-USER RESOURCE ALLOCATION ALGORITHM

In this section, we extend the system model to the communication scenario where there are multiple users in each small cell and multiple MCUs in the macrocell. It is assumed that there are K SCUs and N MCUs, denoted the set as $\mathcal{K} = \{1, 2, \dots, K\}$, $\forall k \in \mathcal{K}$ and $\mathcal{N} = \{1, 2, \dots, N\}$, $\forall n \in \mathcal{N}$. The superposition signals from the SBS can be expressed as

$$x = \sum_{k=1}^K \sqrt{p_k} x_k, \quad (8)$$

where p_k and x_k denote the allocated power and signal from the SBS to the k -th SCU, respectively. Therefore, the signal

Algorithm 1 An Dinkelbach-Based RA for the Single-user IRS-HetNet

- 1: Initialize the maximum number of iterations $L_{\max}$, and the maximum tolerance ε ,
- 2: Set the auxiliary variable $\lambda = 0$ and iteration index $l = 0$.
- 3: **repeat** {Main loop}
- 4: Solve the inner loop problem in **P5** for a given λ .
- 5: Obtain the optimal phase shift factor ϕ_m by using SeDuMi tool [33].
- 6: **if** $A|\mathbf{G}^H \Phi \mathbf{H} + g^{ss}|^2 - \lambda|g^{sm} + \mathbf{F}^H \Phi \mathbf{H}|^2 < \varepsilon$ **then**
- 7: Convergence=**true**
- 8: **return** ϕ_m^* , $\forall m$, obtain the optimal power p^* by (4) and $\lambda^* = \frac{A|\mathbf{G}^H \Phi \mathbf{H} + g^{ss}|^2}{|g^{sm} + \mathbf{F}^H \Phi \mathbf{H}|^2}$.
- 9: **else**
- 10: Set $\lambda(l+1) = \frac{A|\mathbf{G}^H \Phi(l) \mathbf{H} + g^{ss}|^2}{|g^{sm} + \mathbf{F}^H \Phi(l) \mathbf{H}|^2}$ and $l = l + 1$.
- 11: Convergence=**true**
- 12: **end if**
- 13: **until** Convergence=**true** or $l = L_{\max}$.

received at the k -th SCU is

$$y_k = g_k^{ss} x + \mathbf{G}_k^H \Phi \mathbf{H} x + n_k, \quad (9)$$

where g_k^{ss} denotes the channel response from the SBS to the k -th SCU, $\mathbf{G}_k$ denotes the channel response from the IRS to the k -th SCU, $n_k = \sum_{n=1}^N P_n h_k^{ms} + \sigma_k$ denotes the sum of interference plus noise at the k -th SCU, where the background noise σ_k satisfies $\sigma_k \sim \mathcal{CN}(0, \sigma^2)$. h_k^{ms} is the channel response from the MBS to the k -th SCU, P_n is the allocated power from the MBS to the n -th MCU. Since the MBS is often far from the indoor SCUs, the interference power $\sum_{n=1}^N P_n h_k^{ms}$ can be omitted [36]. Thus, the SINR at the k -th SCU can be expressed as

$$\gamma_k^{\text{SCU}} = \frac{p_k |g_k^{ss} + \mathbf{G}_k^H \Phi \mathbf{H}|^2}{|g_k^{ss} + \mathbf{G}_k^H \Phi \mathbf{H}|^2 \sum_{i \neq k}^K p_i + \sigma^2}. \quad (10)$$

Therefore, the achieved total rate for all SCUs is

$$R = \sum_{k=1}^K \log_2(1 + \gamma_k^{\text{SCU}}). \quad (11)$$

The SINR received at the n -th MCU is

$$\gamma_n^{\text{MCU}} = \frac{P_n |h_n^{mm}|^2}{\sum_{k=1}^K p_k |g_n^{sm} + \mathbf{F}_n^H \Phi \mathbf{H}|^2 + \sigma^2}, \quad (12)$$

where h_n^{mm} denotes the channel response from the MBS to the n -th MCU, and g_n^{sm} is the channel gain from the SBS to the n -th MCU.

In order to improve the spectral efficiency, the sum rate achieved by all SCUs can be maximized by solving the

following problem

$$\begin{aligned} \mathbf{P6} \quad & \max_{p_k, \phi_m} \sum_{k=1}^K \log_2 (1 + \gamma_k^{\text{SCU}}) \\ \text{s.t. } & \bar{C}_2 : |\phi_m| = 1, \forall m, \\ & C_5 : \sum_{k=1}^K p_k \leq p^{\max}, \\ & C_6 : \gamma_n^{\text{MCU}} \geq \gamma_n^{\min}, \forall n, \end{aligned}$$

where $\gamma_n^{\min}$ denotes the minimum SINR required by the n -th MCU. However, it is difficult to obtain the optimal solution to **P6**, since the objective function is non-concave with respect to either p_k or ϕ_m . The constraint C_6 is non-convex due to the coupled variables p_k and ϕ_m . As the multiple variables are coupled in **P6**, it is difficult to obtain the globally optimal solutions. Thus, we propose a low-complexity algorithm for solving **P6** approximately in the following section.

Since the variables p_k and ϕ_m are coupled in C_6 and the objective function, we develop an efficient algorithm for **P6** which optimizes p_k and ϕ_m by using the AOM.

1) *Optimizing p_k with given ϕ_m* : Based on C_6 , we have

$$\begin{aligned} I_n^{\text{th}} &= \frac{P_n |h_n^{\text{mm}}|^2}{\gamma_n^{\min}} - \sigma^2 \\ &\geq \sum_{k=1}^K p_k |g_n^{\text{sm}} + \mathbf{F}_n^H \Phi \mathbf{H}|^2, \end{aligned} \quad (13)$$

where I_n^{th} denotes the equivalent interference threshold [30], [31]. As a result, the power allocation problem becomes

$$\begin{aligned} \mathbf{P7} \quad & \max_{p_k} \sum_{k=1}^K \log_2 (1 + \gamma_k^{\text{SCU}}) \\ \text{s.t. } & C_5 : \sum_{k=1}^K p_k \leq p^{\max}, \\ & \bar{C}_6 : \sum_{k=1}^K p_k |g_n^{\text{sm}} + \mathbf{F}_n^H \Phi \mathbf{H}|^2 \leq I_n^{\text{th}}, \forall n. \end{aligned}$$

It is noted that C_5 and $\bar{C}_6$ are linear constraints. But the objective function is nonconvex. Based on the SCALE algorithm in [32], for any $z > 0$, we have the following bound

$$\log_2(1+z) \geq \alpha \log_2 z + \beta, \quad (14)$$

where $\alpha = \frac{z_0}{1+z_0}$ and $\beta = \log_2(1+z_0) - \alpha \log_2 z_0$ are the auxiliary variables. The relationship is tight at $z = z_0$, and α , β are the approximation constants. Therefore, we define

$$R = \sum_{k=1}^K \alpha_k \log_2 \gamma_k + \sum_{k=1}^K \beta_k, \quad (15)$$

which is a lower bound of the sum rate achieved by all SCUs. Note that the relaxation is still a nonconvex form due to the d.c. (difference of convex) structure. With the Logarithmic transformation $\bar{p}_k = \ln p_k, \forall k$, we have the following convex

optimization problem

$$\begin{aligned} \mathbf{P8} \quad & \max_{\bar{p}_k} - \sum_{k=1}^K \alpha_k \log_2 \left(\sigma^2 + |g_k^{\text{ss}} + \mathbf{G}_k^H \Phi \mathbf{H}|^2 \sum_{i \neq k}^K e^{\bar{p}_i} \right) \\ & + \sum_{k=1}^K \alpha_k \log_2 \left(|g_k^{\text{ss}} + \mathbf{G}_k^H \Phi \mathbf{H}|^2 \right) \\ & + \sum_{k=1}^K \alpha_k \bar{p}_k - \sum_{k=1}^K \beta_k \\ \text{s.t. } & \bar{C}_5 : \sum_{k=1}^K e^{\bar{p}_k} \leq p^{\max}, \\ & \bar{C}_6 : \sum_{k=1}^K e^{\bar{p}_k} |g_n^{\text{sm}} + \mathbf{F}_n^H \Phi \mathbf{H}|^2 \leq I_n^{\text{th}}, \forall n. \end{aligned}$$

Note that **P8** is a standard concave maximization problem since the log-sum-exp is convex [37]. Considering the convexity of **P8**, the optimal power allocation can be obtained by the Lagrange dual function as

$$\begin{aligned} L(\bar{p}_k, \mu, \vartheta_n) &= \sum_{k=1}^K \alpha_k \bar{p}_k - \sum_{k=1}^K \beta_k + \mu \left(p^{\max} - \sum_{k=1}^K e^{\bar{p}_k} \right) \\ & - \sum_{k=1}^K \alpha_k \log_2 \left(\sigma^2 + |g_k^{\text{ss}} + \mathbf{G}_k^H \Phi \mathbf{H}|^2 \sum_{i \neq k}^K e^{\bar{p}_i} \right) \\ & + \sum_{n=1}^N \vartheta_n \left(I_n^{\text{th}} - \sum_{k=1}^K e^{\bar{p}_k} |g_n^{\text{sm}} + \mathbf{F}_n^H \Phi \mathbf{H}|^2 \right) \\ & + \sum_{k=1}^K \alpha_k \log_2 \left(|g_k^{\text{ss}} + \mathbf{G}_k^H \Phi \mathbf{H}|^2 \right), \end{aligned} \quad (16)$$

where μ and ϑ_n are the non-negative Lagrange multipliers. Based on the same approach, we have the following closed-form solution

$$p_k = \left[\frac{\alpha_k}{\mu + \sum_{n=1}^N \vartheta_n |g_n^{\text{sm}} + \mathbf{F}_n^H \Phi \mathbf{H}|^2} \right]^+, \quad (17)$$

where $[x]^+ = \max\{0, x\}$.

Based on the sub-gradient method, the Lagrange multipliers can be calculated by

$$\mu^{l+1} = \left[\mu^l - d_1^l \times \left(p^{\max} - \sum_{k=1}^K p_k \right) \right]^+, \quad (18)$$

$$\vartheta_n^{l+1} = \left[\vartheta_n^l - d_2^l \times \left(I_n^{\text{th}} - \sum_{k=1}^K p_k |g_n^{\text{sm}} + \mathbf{F}_n^H \Phi \mathbf{H}|^2 \right) \right]^+, \quad (19)$$

where l is the iteration number. d_1^l and d_2^l denote the sufficiently small positive step sizes satisfying $\sum_{l=1}^{\infty} d_i^l = \infty, \lim_{l \rightarrow \infty} d_i^l = 0, \forall i = \{1, 2\}$ [31]. The dual variables $\mu(l)$ and $\vartheta_n(l)$ will converge to the optimal values μ^* and $\vartheta_n^*, \forall n$ as $l \rightarrow \infty$ [38], [39]. Note that the duality gap for the problem

P8 is zero and the solution is unique. As a result, the primal variable $p_k^*(\mu(l), \vartheta_n(l))$ can reach its optimal value $p_k^*, \forall k$.

2) *Optimizing ϕ_m with given p_k* : Now we perform the optimization over ϕ_m with the fixed p_k . Then **P8** is equivalent to

$$\begin{aligned} \mathbf{P9} \quad & \max_{\phi_m} \sum_{k=1}^K \frac{\alpha_k p_k |g_k^{ss} + \mathbf{G}_k^H \Phi \mathbf{H}|^2}{|g_k^{ss} + \mathbf{G}_k^H \Phi \mathbf{H}|^2 \sum_{i \neq k}^K p_i + \sigma^2} \\ \text{s.t. } & \bar{C}_2 : |\phi_m| = 1, \forall m, \\ & \bar{C}_6 : \sum_{k=1}^K p_k |g_n^{sm} + \mathbf{F}_n^H \Phi \mathbf{H}|^2 \leq I_n^{th}, \forall n, \end{aligned}$$

P9 is the sum of multiple-ratio fractional programming problems, and the non-convexity introduced by the fractional objective function and the non-convex unit-modulus constraint C_4 . We adopt a relaxation method to solve **P9** efficiently.

Define $\tilde{\mathbf{F}} = \bar{\mathbf{F}} \bar{\mathbf{F}}^H$, based on $|x + y| \leq |x| + |y|$, and $\bar{\mathbf{F}} = \text{diag}(\mathbf{F}_n) \mathbf{H}$, the constraint $\bar{C}_5$ becomes

$$\begin{aligned} |g_n^{sm} + \mathbf{F}_n^H \Phi \mathbf{H}|^2 &\leq |g_n^{sm}|^2 + |\phi^H \tilde{\mathbf{F}}|^2 \\ &= |g_n^{sm}|^2 + \phi^H \tilde{\mathbf{F}} \phi \leq \frac{I_n^{th}}{\sum_{k=1}^K p_k}. \end{aligned} \quad (20)$$

Thus we have

$$\phi^H \tilde{\mathbf{F}} \phi \leq \bar{I}_n^{th}, \forall n, \quad (21)$$

where $\bar{I}_n^{th} = \frac{I_n^{th}}{\sum_{k=1}^K p_k} - |g_n^{sm}|^2$ is the equivalent interference level for the n -th MCU. Thus, **P9** can be reformulated as

$$\begin{aligned} \mathbf{P10} \quad & \max_{\phi_m, y_k} \sum_{k=1}^K y_k \\ \text{s.t. } & \bar{C}_2 : |\phi_m| = 1, \forall m, \\ & C_7 : \frac{\alpha_k p_k |g_k^{ss} + \mathbf{G}_k^H \Phi \mathbf{H}|^2}{|g_k^{ss} + \mathbf{G}_k^H \Phi \mathbf{H}|^2 \sum_{i \neq k}^K p_i + \sigma^2} \geq y_k, \forall k, \\ & C_8 : \phi^H \tilde{\mathbf{F}} \phi \leq \bar{I}_n^{th}, \forall n, \end{aligned}$$

where $y_k \geq 0$ is an auxiliary variable. Define $\bar{\mathbf{G}}_k = \text{diag}(\mathbf{G}_k) \mathbf{H}$, C_7 can be rewritten as

$$\phi^H \bar{\mathbf{G}}_k \bar{\mathbf{G}}_k^H \phi + 2\text{Re}\{g_k^{ss,*} \bar{\mathbf{G}}_k^H \phi\} + f_k \leq 0 \quad (22)$$

where $(\cdot)^*$ denotes the conjugate of vector, $\text{Re}(\cdot)$ denotes the real part, and $f_k = |g_k^{ss}|^2 + \frac{y_k \sigma^2}{\sum_{i \neq k}^K p_i - \alpha_k p_k}$. What's more, $\bar{C}_2$

can be rewritten as

$$\phi^H \mathbf{U} \phi = 1, \quad (23)$$

where $\mathbf{U} \in R^{M \times M}$ is a symmetric matrix with elements of zeros, except for $u_{m,m} = 1$.

Thus, we have

$$\begin{aligned} \mathbf{P11} \quad & \max_{\phi, y_k} \sum_{k=1}^K y_k \\ \text{s.t. } & C_4 : \phi^H \mathbf{U} \phi = 1, \\ & \bar{C}_5 : \phi^H \tilde{\mathbf{F}} \phi \leq \bar{I}_n^{th}, \forall n, \\ & C_6 : \bar{f}_k + f_k \leq 0, \end{aligned}$$

where $\bar{f}_k = \phi^H \bar{\mathbf{G}}_k \bar{\mathbf{G}}_k^H \phi + 2\text{Re}\{g_k^{ss,*} \bar{\mathbf{G}}_k^H \phi\}$. **P11** is a convex optimization problem with the quadratic constraints. Thus, the Lagrangian of **P11** is

$$\begin{aligned} L(\phi, y_k, \kappa, \rho_n, \varpi_k) &= - \sum_{k=1}^K y_k + \kappa (\phi^H \mathbf{U} \phi - 1) \\ &+ \sum_{k=1}^K \varpi_k (\bar{f}_k + f_k) + \sum_{n=1}^N \rho_n (\phi^H \tilde{\mathbf{F}} \phi - \bar{I}_n^{th}), \end{aligned} \quad (24)$$

where κ, ϖ_k, ρ_n are the Lagrange multipliers. Based on KKT conditions [37], the optimal value of y_k can be obtained as

$$y_k^* = \left[\frac{\alpha_k p_k + \sigma \sqrt{\varpi_k \alpha_k p_k}}{\sum_{j \neq k}^K p_j} \right]^+, \quad (25)$$

where the Lagrange multipliers can be updated by using the subgradient methods, i.e.,

$$\kappa^{l+1} = [\kappa^l + d_3^l \times (\phi^H \mathbf{U} \phi - 1)]^+, \quad (26)$$

$$\rho_n^{l+1} = [\rho_n^l + d_4^l \times (\phi^H \tilde{\mathbf{F}} \phi - \bar{I}_n^{th})]^+, \quad (27)$$

$$\varpi_k^{l+1} = [\varpi_k^l + d_5^l \times (\bar{f}_k + f_k)]^+, \quad (28)$$

where d_3^l, d_4^l and d_5^l are the step sizes.

In order to solve the phase shift of the IRS, based on a Schur complement, the dual problem of **P11** can be formulated as

$$\begin{aligned} \mathbf{P12} \quad & \max \gamma \\ \text{s.t. } & \gamma \geq 0, \\ & \tilde{\mathbf{M}} \succcurlyeq 0, \end{aligned}$$

where $\tilde{\mathbf{M}} = \begin{bmatrix} B_1 & B_2 \\ B_2^T & B_3 \end{bmatrix}$, $B_1 = \kappa \mathbf{U} + \sum_{k=1}^K \varpi_k \bar{\mathbf{G}}_k \bar{\mathbf{G}}_k^H + \sum_{n=1}^N \rho_n \tilde{\mathbf{F}}$, $B_2 = \sum_{k=1}^K \varpi_k \text{Re}\{g_k^{ss,*} \bar{\mathbf{G}}_k^H\}$, and $B_3 = \sum_{k=1}^K \varpi_k f_k - \sum_{k=1}^K y_k - \kappa - \sum_{n=1}^N \rho_n \bar{I}_n^{th} - \gamma$. γ is an auxiliary variable. **P12** is an SDP problem and the Slater's constraint qualification is satisfied [37]. Particularly, an iterative-based RA algorithm for the multiuser IRS-based HetNet is summarized in Algorithm 2.

IV. SIMULATION RESULTS

In this section, simulation results are given to investigate the performance of the proposed RA scheme in the IRS-enabled HetNet. A spectrum-sharing small cell is randomly distributed in the coverage area of the macrocell. SCUs are uniformly distributed in the coverage area of their associated SBS. The

Algorithm 2 An Iterative Based RA Algorithm for Multiuser IRS-enabled HetNet

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1: Input:  $M, K, N, p^{\max}, I_n^{th}, \sigma^2, \mathbf{G}_k, \mathbf{H}, \mathbf{F}_n, g_n^{sm}, g_n^{ss}, h_n^M, \varepsilon$ 
   and  $L_{\max}$ .
2: Initialization:  $\alpha_k, \beta_k, l = 0, p_k(0) = \frac{P^{\max}}{K}, \mu(0) > 0, \vartheta_n(0) > 0, \kappa(0) > 0, \rho_n(0) > 0, \varpi_k(0) > 0,$ 
    $d_3(0), d_4(0), d_5(0)$ , and  $\Phi(0) = \frac{\pi}{2} \mathbf{I}_M$ .
3: while  $l < L_{\max}$  do
4:   Given  $\Phi$  update  $p_k, \forall k$ :
5:   for  $l = 1 : 1 : L_{\max}$  do
6:     Update transmit power  $p_k$  by (17);
7:     Update Lagrange multipliers  $\mu$  and  $\vartheta_n$  by (18) and (19);
8:     Update the auxiliary variable  $\alpha_k(l+1) = \frac{\gamma_k(l)}{1+\gamma_k(l)}$ 
       and  $\beta_k(l+1) = \log_2(1+\gamma_k(l)) - \alpha(l) \log_2(\gamma_k(l))$ ;
9:     Until  $\|\mathbf{p}(l+1) - \mathbf{p}(l)\|^2 < \varepsilon$ ; Obtain the optimal
       transmit power  $\mathbf{p}^* = \mathbf{p}(l+1)$ , where  $\mathbf{p}(l+1) = [p_1(l+1), p_2(l+1), \dots, p_K(l+1)]^T$ .
10:   end for
11:   Given  $p_k^*, \forall k$  update  $\Phi$ :
12:   for  $l = 1 : L_{\max}$  do
13:     Update the auxiliary variable  $y_k$  by (25);
14:     Update the Lagrange multipliers  $\kappa, \rho_n$ , and  $\varpi_k$  by (26)-(28), respectively;
15:     Until  $\|\mathbf{y}(l+1) - \mathbf{y}(l)\|^2 < \varepsilon$ , where
        $\mathbf{y}(l) = [y_1(l), y_2(l), \dots, y_K(l)]^T$ ; Obtain parameters
        $y_k, \kappa, \rho_n$ , and  $\varpi_k$ .
16:     Obtain the phase shift  $\Phi$  by solving the problem P12
       via SDP.
17:     if  $\|\Phi(l+1) - \Phi(l)\|^2 < \varepsilon$  then
18:        $\Phi^* = \Phi(l+1)$ , break;
19:     else
20:        $l = l + 1$ ;
21:     end if
22:   end for
23: end while
24: Output:  $\mathbf{p}$  and  $\Phi$ .

```

coverage radii of the macrocell and small cell are 500 m and 20 m, respectively. The distance between the SBS and the IRS is 10 m. The channel model is the same as in [31]. The stopping criterion for convergence is $\varepsilon = 10^{-6}$. The noise power is $\sigma^2 = -100$ dBm. The channel bandwidth is 10 MHz [40]. For performance comparison, we provide the traditional RA scheme without IRS (e.g., $\Phi = 0$) as the benchmark.

A. Single-user Case

First, we consider a single-user IRS-enabled HetNet with the target SINR of MCU $\gamma^{\min} = 2$ dB. The unit bandwidth is considered for simplicity. Fig. 2 depicts the data rate of the SCU versus the transmit power at the MBS. From the figure, the data rate of the SCU improves quickly as the transmit power of the MBS increases. The reason is that, the large transmit power of the MBS (e.g., P) increases the feasible region of transmit power of the SCU from the constraint $C1$, which allows more transmit power from the SBS to improve

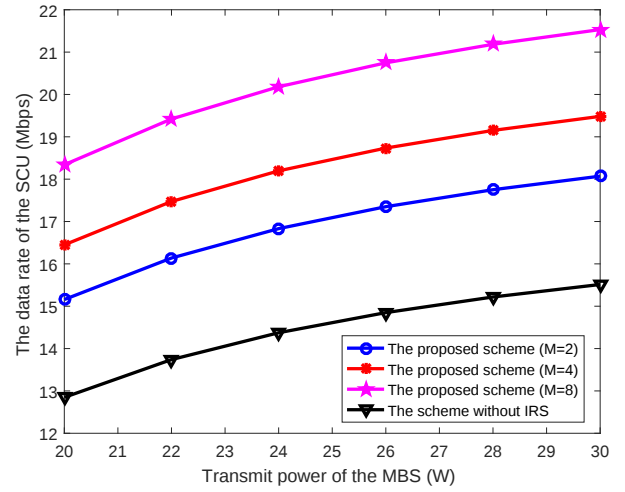


Fig. 2. The achieved data rate of the SCU under different transmit power of MBS.

system performance. Besides, the figure also shows that the data rate under the proposed scheme is better than that of the scheme without IRS, which indicates that the IRS can further improve the performance of HetNets in a passive reflecting way. Moreover, with the increasing number of reflecting elements at the IRS, the data rate increases heavily, which indicates that a larger number of passive reflecting elements leads to better performance.

Fig. 3 shows the data rate of the SCU versus the minimum SINR requirement for the MCU, $\gamma^{\min}$. The transmit power of MBS is assumed to be 20 W. With the increasing $\gamma^{\min}$, the data rate of the SCU decreases considerably. Because under the fixed transmit power at the MBS, the allowed transmit power of SCU becomes smaller to guarantee less interference to the MCU for the SINR requirement. It is noted that in terms of the achieved transmission performance, i.e., the achieved data rate, the proposed scheme (e.g., data rate) is still better than that of the scheme without IRS. Moreover, the performance gap of the SCU under the two schemes becomes small since the small transmit power leads to less interference to the MCU.

Fig. 4 compares the transmit power at the SBS versus the number of reflecting elements (e.g., M). First, it is observed that the required transmit power of the proposed scheme is significantly lower than that without the IRS under different transmit power at the MBS. This demonstrates that the energy consumption of the system can be reduced when the IRS is adopted. Moreover, one can observe that the received transmit power of the SBS decreases with the increasing number of reflecting elements. This is expected since the larger reflecting elements provide more multipath interference to the MCU. The available transmit power of the SBS degrades for guaranteeing the QoS of the MCU. Finally, when the transmit power at the MBS is increased, the available transmit power at the SBS is also increased. Because the large transmit power at the MBS can allow more transmit power of the SBS to improve the communication quality of the SCU according to (3).

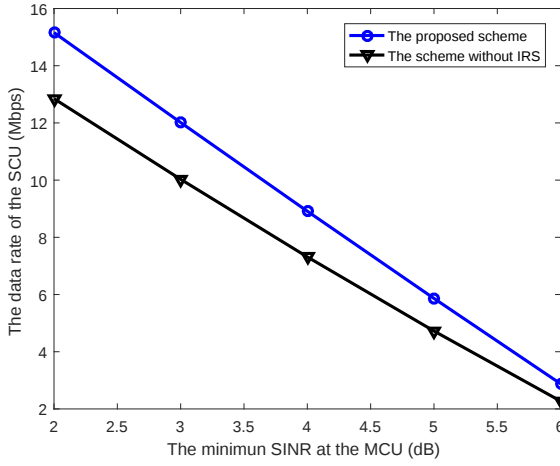


Fig. 3. The achieved data rate of the SCU under different SINR thresholds of the MCU.

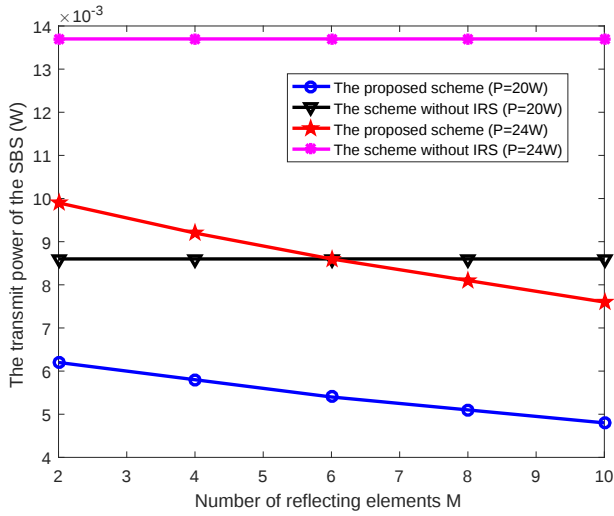


Fig. 4. Transmit power of SBS versus the number of reflecting elements.

B. Multi-user Case

Next, we consider a multiuser system with three SCUs $K = 3$, two MCUs $N = 2$ and four reflecting elements $M = 4$. The SCUs are randomly distributed in the small cell network. Assume each MCU receiver has the same interference power threshold. The maximum transmit power of the SBS is $P^{\max} = 1$ W, and the interference power threshold is $I_n^{th} = 10^{-3}$ mW [27], [31].

Before comparing the performance in the multi-user system, we first show the convergence behaviour of the proposed scheme in Fig. 5. It is observed that the transmit power allocated by the SBS to the SCUs can quickly reach the convergence within a small number of iterations (e.g., less than 8 iterations), which demonstrates good convergence of the proposed scheme in the multiuser IRS-enabled HetNet.

Fig. 6 shows the sum rate of all SCUs versus the number of reflecting elements with different SCUs. It is observed that the total data rate achieved by the SCUs increases with the larger reflecting element since it provides more reflecting signals to the SCUs. The reflecting signals can enhance signal strength

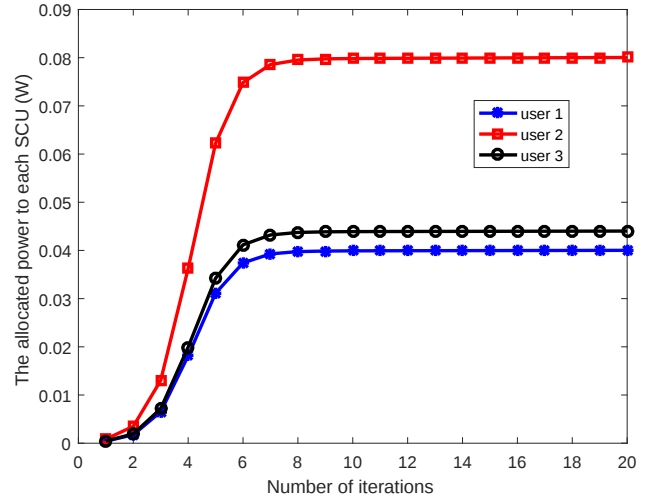


Fig. 5. Convergence behaviour of the proposed scheme.

at the receivers. However, the data rate achieved by all SCUs under the traditional scheme without IRS is not affected by the number of reflecting elements. Besides, the total rate of SCUs with larger number of users is bigger than that with small number of users. The rate gap under the small number of reflecting elements (e.g., $M = 2$) is larger than that under the large number of reflecting elements (e.g., $M = 10$). Because the interference among different users is small due to less transmission path, the total rate is decided by the number of users. Thus there is a big performance gap at the region with small reflecting elements. However, due to the effect of the cross-tier interference constraint (e.g., $\bar{C}_5$), the overall performance of the small cell is limited. It is impossible to unrestrictedly improve the performance with the increasing number of reflecting elements.

Fig. 7 shows the total rate of SCUs versus different interference thresholds of the MCU, I_n^{th} . The total rate of SCUs increases with the increasing interference threshold of the MCU. The higher interference threshold means that the MCU can tolerate higher interference from other BSs and IRS reflection. Correspondingly, the SBS can allocate more transmit power to SCUs for obtaining higher data rate. Moreover, the proposed scheme with large number of reflecting elements achieves better performance than other two cases. The reason is that the IRS can enhance the system performance by providing multiple flexible transmission paths.

V. CONCLUSIONS

In this paper, we considered the downlink transmission in an IRS-enabled HetNet and presented two computationally efficient RA algorithms for optimizing the transmit power at the SBS and the phase shifts at the IRS under the single user and the multi-user scenarios, respectively. For the single-user case, we developed an optimal RA algorithm and obtained a closed-form solution. For the multi-user scenario, the RA algorithm was designed by using an alternating approach, where the non-convex problem is converted into an SDP problem by using the successive convex approximation. The

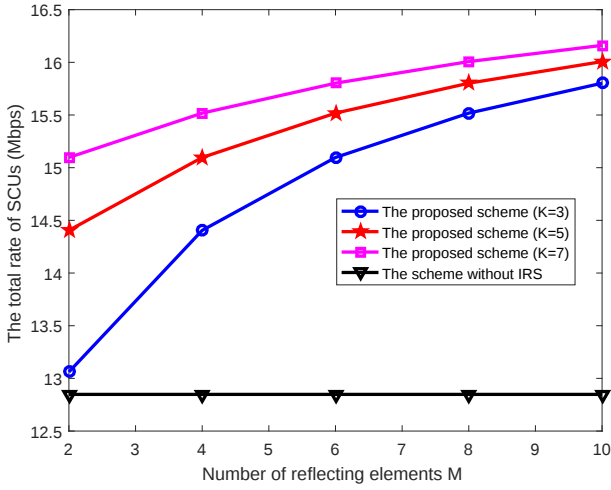


Fig. 6. The data rate of all SCUs under different number of reflecting elements.

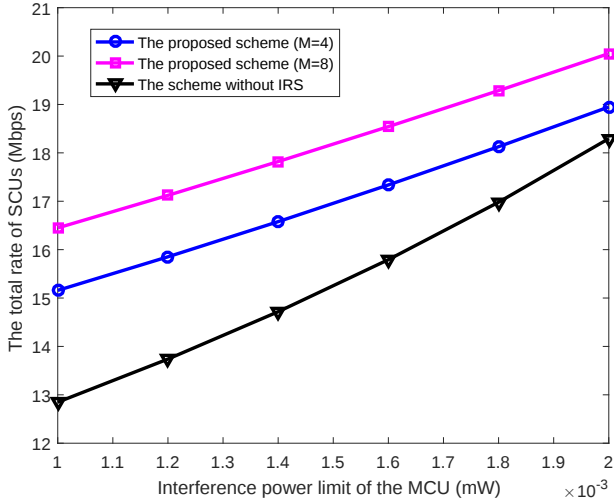


Fig. 7. The data rate of all SCUs under different interference power level of the MCU.

numerical results showed that the proposed algorithm can improve the total data rate of SCUs with guaranteeing the QoS of the MCU.

APPENDIX A THE PROOF OF THEOREM 1

By following a similar approach as in [29], the Theorem 1 can be proved by the following two steps.

First, the sufficient condition of Theorem 1 is proved. Define the maximum objective value as $\lambda^* = \frac{A|G^H \Phi^* H + g^{ss}|^2}{|g^{sm} + F^H \Phi^* H|^2}$, where $\Phi^* = [\phi_1^*, \phi_2^*, \dots, \phi_M^*]$ represents the optimal phase shift policy at the IRS. It is observed that λ^* holds, i.e.,

$$\lambda^* = \frac{A|G^H \Phi^* H + g^{ss}|^2}{|g^{sm} + F^H \Phi^* H|^2} \geq \frac{A|G^H \Phi H + g^{ss}|^2}{|g^{sm} + F^H \Phi H|^2}, \quad (\text{A.1})$$

where Φ is the feasible phase shift in **P2**. Then, based on

(A.1), we can obtain the following formulas:

$$\begin{cases} A|G^H \Phi H + g^{ss}|^2 - \lambda^* |g^{sm} + F^H \Phi H|^2 \leq 0 \\ A|G^H \Phi^* H + g^{ss}|^2 - \lambda^* |g^{sm} + F^H \Phi^* H|^2 = 0. \end{cases} \quad (\text{A.2})$$

As a result, we have the conclusion that $\max_{\phi_m} A|G^H \Phi H + g^{ss}|^2 - \lambda^* |g^{sm} + F^H \Phi H|^2 = 0$, and it is achievable under the optimal policy Φ^* . The sufficient condition has been proved.

Second, the necessary condition is provided. Assume the optimal phase policy is $\bar{\Phi}^*$, we have $A|G^H \bar{\Phi}^* H + g^{ss}|^2 - \lambda^* |g^{sm} + F^H \bar{\Phi}^* H|^2 = 0$. For any feasible solution Φ , it can be written as

$$\begin{aligned} & A|G^H \Phi H + g^{ss}|^2 - \lambda^* |g^{sm} + F^H \Phi H|^2 \\ & \leq A|G^H \bar{\Phi}^* H + g^{ss}|^2 - \lambda^* |g^{sm} + F^H \bar{\Phi}^* H|^2 \\ & = 0. \end{aligned} \quad (\text{A.3})$$

Based on (A.3), we have

$$\begin{cases} \frac{A|G^H \Phi H + g^{ss}|^2}{|g^{sm} + F^H \Phi H|^2} \leq \lambda^* \\ \frac{A|G^H \bar{\Phi}^* H + g^{ss}|^2}{|g^{sm} + F^H \bar{\Phi}^* H|^2} = \lambda^*. \end{cases} \quad (\text{A.4})$$

Therefore, the optimal phase shift policy $\bar{\Phi}^*$ for the converted objective function is also the optimal RA scheme for the original objective function. Thus, the necessary condition of Theorem 1 is completed.

APPENDIX B THE PROOF OF THEOREM 2

According to **P3**, an equivalent objective function is given by

$$Q(\lambda) = \max_{\phi_m} A|G^H \Phi H + g^{ss}|^2 - \lambda |g^{sm} + F^H \Phi H|^2. \quad (\text{B.1})$$

Assume there are two optimal auxiliary variables λ_1 and λ_2 ($\lambda_1 > \lambda_2$) for the optimal phase shift policies Φ_1 and Φ_2 , respectively. Then

$$\begin{aligned} Q(\lambda_2) &= A|G^H \Phi_2 H + g^{ss}|^2 - \lambda_2 |g^{sm} + F^H \Phi_2 H|^2 \\ &> A|G^H \Phi_1 H + g^{ss}|^2 - \lambda_2 |g^{sm} + F^H \Phi_1 H|^2 \\ &> A|G^H \Phi_1 H + g^{ss}|^2 - \lambda_1 |g^{sm} + F^H \Phi_1 H|^2 \\ &= Q(\lambda_1). \end{aligned} \quad (\text{B.2})$$

Therefore, $Q(\lambda)$ is a strictly decreasing function with the variable λ .

Define Φ' be any feasible solution for **P3** and $\lambda' = \frac{A|G^H \Phi' H + g^{ss}|^2}{|g^{sm} + F^H \Phi' H|^2}$, we have

$$\begin{aligned} Q(\lambda') &= \max_{\phi_m} A|G^H \Phi H + g^{ss}|^2 - \lambda' |g^{sm} + F^H \Phi H|^2 \\ &\geq A|G^H \Phi' H + g^{ss}|^2 - \lambda' |g^{sm} + F^H \Phi' H|^2 = 0. \end{aligned} \quad (\text{B.3})$$

As a result, we have $Q(\lambda) \geq 0$. The proof is completed.

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